Xtreme 400 EP helicopter detail features and specifications

Features:

3D-Aerobatic, collective pitch, 6-channel control.

Fully equipped ball bearings (31 micro bearings).

Streamline cabin and canopy.

2-bearing tail pitch slider produces precision tail control.

Belt driven tail rotor.

Lightweight paddles.

Boom-mounted tail rotor servo.

Wide landing gear stance.

Extended aluminum battery tray.

Ball-end control linkages.

Seesaw head with bell-hiller system.

Fiberglass composite main frame.

Strong, lightweight aluminum tail boom.

Durable tail boom supports.

Loaded with a 400-class brushed motor with enough power for acro flight.

Only a short time needed for completion (95% factory assembled).

Extensive upgrade parts and option parts available.

Specification:

Overall length: 575mm (including cabin & canopy).

Main rotor diameter: 645mm. Tail rotor diameter: 140mm.

Motor: 400-class brushed motor (KV3700 brushless motor for option).

Flying weight: 520g (It may vary according to size of a battery pack and R/C gears.).

Main rotor blades: plastic coated formed blades (included) or fiber(option).

Flying duration: 6~8 minutes with 11.1v/1600mah Li-Po battery.

Items needed for assembly:

6 (or more) channel heli-capable transmitter.

4 Micro servos.

6 (or more) channel micro receiver.

Gyro (heading hold gyro is recommended).

ESC (20A~30A).

Battery: Li-Po battery (11.1v/1600mah).

Charger: Li-Po battery charger.